Classical Mechanics Tutorial

Engineering Physics

Indian Institute of Information Technology, Allahabad

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We shall first obtain the Lagrangian of the system.

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- We will then find the generalized momenta and express q in terms of p

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- We will then find the generalized momenta and express q in terms of p
- Finally we shall use $H = \sum p\dot{q} L$ to obtain the Hamiltonian

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Lastly, since $p = \partial L / \partial \dot{x} = m \dot{x} \implies \dot{x} = p/m$, We get

$$T = \frac{p^2}{2m} \tag{3}$$

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So using these equations

$$H = \sum p\dot{x} - L$$
(4)
= $p\frac{p}{m} - \frac{p^2}{2m} + \frac{1}{2}kx^2 + \frac{1}{4}bx^4$ (5)

where

$$L = \frac{1}{2}m\dot{x}^2 - \frac{1}{2}kx^2 + \frac{1}{4}bx^4$$
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$$H = \sum p \dot{x} - L$$
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= $p^{p} p^{2} + \frac{1}{2} l w^{2} + \frac{1}{2} b w^{4}$ (5)

$$=p\frac{p}{m}-\frac{p}{2m}+\frac{1}{2}kx^{2}+\frac{1}{4}bx^{4}$$
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where

$$L = \frac{1}{2}m\dot{x}^2 - \frac{1}{2}kx^2 + \frac{1}{4}bx^4$$
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After doing the simple algebra, we get

$$H = \frac{p^2}{2m} + \frac{1}{2}kx^2 + \frac{1}{4}bx^4 \tag{7}$$

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So using these equations

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After doing the simple algebra, we get

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We can now figure out the equations of motion.

We have found out that

$$H = \frac{p^2}{2m} + \frac{1}{2}kx^2 + \frac{1}{4}bx^4$$
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The Hamilton's equation of motion are given by

$$\dot{x} = \frac{\partial H}{\partial p} \quad , \quad -\dot{p} = \frac{\partial H}{\partial x}$$
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We can easily calculate them to be

$$\dot{x} = p/m \tag{10}$$
$$-\dot{p} = kx + bx^3 \tag{11}$$

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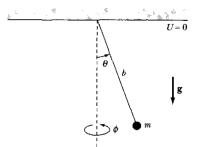
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Now we can differentiate 10 and use 11 to write $m\ddot{x} = \dot{p} \implies m\ddot{x} + kx + bx^3 = 0$

Let us look at another problem: Use the Hamiltonian method to find the equations of motion for a spherical pendulum of mass m and length b.

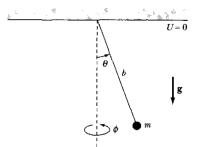
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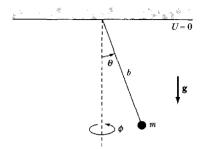


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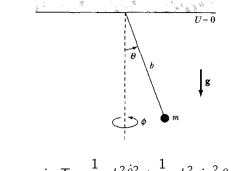
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The generalized coordinates are θ and ϕ .

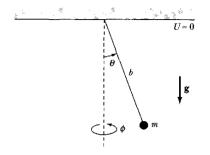


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The kinetic energy is $T = \frac{1}{2}mb^2\dot{\theta}^2 + \frac{1}{2}mb^2\sin^2\theta\dot{\phi}^2$ and the potential energy is $U = -mgb\cos\theta$

We can now write the Lagrangian as

$$L = \frac{1}{2}mb^2\dot{\theta}^2 + \frac{1}{2}mb^2\sin^2\theta\dot{\phi}^2 + mgb\cos\theta \qquad (12)$$

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and calculate the generalized momenta as

$$p_{\theta} = \frac{\partial L}{\partial \dot{\theta}} = mb^2 \dot{\theta} \tag{13}$$

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We then calculate the Hamiltonian using $H = p_{ heta} \dot{ heta} + p_{\phi} \dot{\phi} - L$

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$$H = p_{\theta} \frac{p_{\theta}}{mb^2} + p_{\phi} \frac{p_{\phi}}{mb^2 \sin^2 \theta} - \frac{1}{2} mb^2 \left(\frac{p_{\theta}}{mb^2}\right)^2 - \frac{1}{2} mb^2 \sin^2 \theta \left(\frac{p_{\phi}}{mb^2 \sin^2 \theta}\right)^2 - mgb \cos \theta$$

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$$H = \frac{p_{\theta}^2}{2mb^2} + \frac{p_{\phi}^2}{2mb^2\sin^2\theta} - mgb\cos\theta$$
(15)

Since,
$$H = \frac{p_{\theta}^2}{2mb^2} + \frac{p_{\phi}^2}{2mb^2\sin^2\theta} - mgb\cos\theta$$

We now calculate Hamilton's equations of motion as follows:

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$$\dot{\theta} = \frac{\partial H}{\partial p_{\theta}} = \frac{p_{\theta}}{mb^2}$$
 (16)

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$$\dot{\phi} = \frac{\partial H}{\partial p_{\phi}} = \frac{p_{\phi}}{mb^2 \sin^2 \theta}$$
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$$\dot{p_{\theta}} = -\frac{\partial H}{\partial \theta} = \frac{p_{\phi}^2 \cos \theta}{mb^2 \sin^3 \theta} - mgb \sin \theta$$
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Since,
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$$\dot{p_{\phi}} = -\frac{\partial H}{\partial \phi} = 0$$
 (19)

Because ϕ is a cyclic coordinate, the momentum p_{ϕ} about the symmetry axis is constant