COMP171

# Depth-First Search

# Summary of BFS

- **Graph and representations**
- **BFS, and BFS tree**
- Complexity of BFS

Graph / Slide 3

# Two representations: Adjacency List vs. Matrix

Two sizes: n = |V| and m=|E|,
 m = O(n<sup>2</sup>)

### Adjacency List

I More compact than adjacency matrices if graph has few edges

- Requires a scan of adjacency list to check if an edge exists
- Requires a scan to obtain all edges!

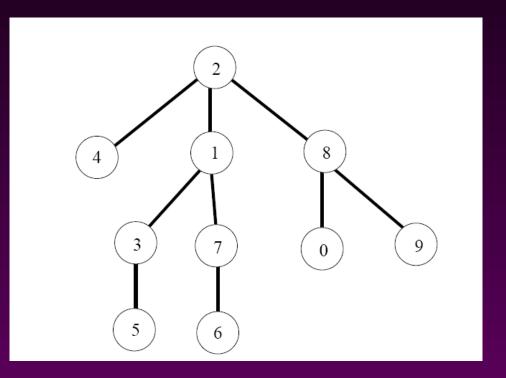
#### Adjacency Matrix

- □ Always require n<sup>2</sup> space
  - This can waste a lot of space if the number of edges are sparse
- I find if an edge exists in O(1)
- Obtain all edges in O(n)

Graph / Slide 4

## BFS Tree

#### BFS tree for vertex s=2.



11.

## Time Complexity of BFS (Using Adjacency List)

#### Algorithm BFS(s)**Input:** *s* is the source vertex **Output:** Mark all vertices that can be visited from s. for each vertex v 1 2. do flaq[v] := false; 3. Q = empty queue;flag[s] := true;4. enqueue(Q, s);5. while Q is not empty 6. do v := dequeue(Q);7. 8. for each w adjacent to v do if flag[w] = false9.

- 9. do if flag[w] = false10. then flag[w] := true;
  - enqueue(Q, w)

# O(n + m)

# Each vertex will enter Q at most once.

Each iteration takes time proportional to deg(v) + 1 (the number 1 is to account for the case where deg(v) = 0 --- the work required is 1, not 0).

## Time Complexity of BFS (Using Adjacency Matrix)

#### Algorithm BFS(s)

**Input:** *s* is the source vertex

**Output:** Mark all vertices that can be visited from *s*.

- 1. for each vertex v
- 2. **do** flag[v] := false;
- 3. Q = empty queue;
- 4. flag[s] := true;
- 5. enqueue(Q, s);

11.

- 6. while Q is not empty
- 7. **do** v := dequeue(Q);
- 8. **for** each w adjacent to v
- 9. **do if** flag[w] = false
- 10. then flag[w] := true;
  - enqueue(Q,w)



Finding the adjacent vertices of v requires checking all elements in the row. This takes linear time O(n).

Summing over all the n iterations, the total running time is  $O(n^2)$ .

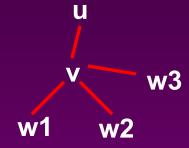
So, with adjacency matrix, BFS is  $O(n^2)$ independent of the number of edges m. With adjacent lists, BFS is O(n+m); if  $m=O(n^2)$  like in a dense graph,  $O(n+m)=O(n^2)$ .

# Depth-First Search (DFS)

- DFS is another popular graph search strategy
  - Idea is similar to pre-order traversal (visit node, then visit children recursively)
- DFS can provide certain information about the graph that BFS cannot
  - It can tell whether we have encountered a cycle or not

# DFS Algorithm

- DFS will continue to visit neighbors in a recursive pattern
  - Whenever we visit v from u, we recursively visit all unvisited neighbors of v. Then we backtrack (return) to u.
  - Note: it is possible that w2 was unvisited when we recursively visit w1, but became visited by the time we return from the recursive call.



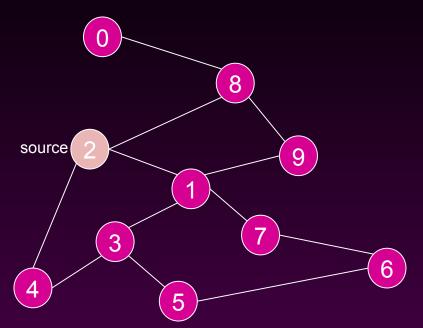
# DFS Algorithm

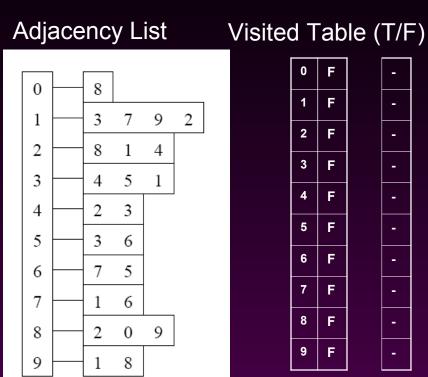
#### Algorithm DFS(s)1. for each vertex v Flag all vertices as not **do** flag[v] := false;2. visited RDFS(s);3. Algorithm RDFS(v)Flag yourself as visited flag[v] := true;1. for each neighbor w of v 2. 3. do if flag[w] = falseFor unvisited neighbors, then RDFS(w); 4. call RDFS(w) recursively

We can also record the paths using pred[].

Graph / Slide 10

# Example

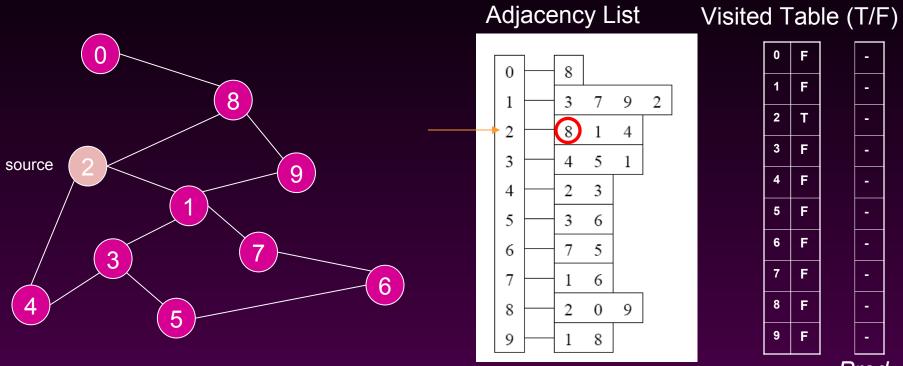




Pred

Initialize visited table (all False)

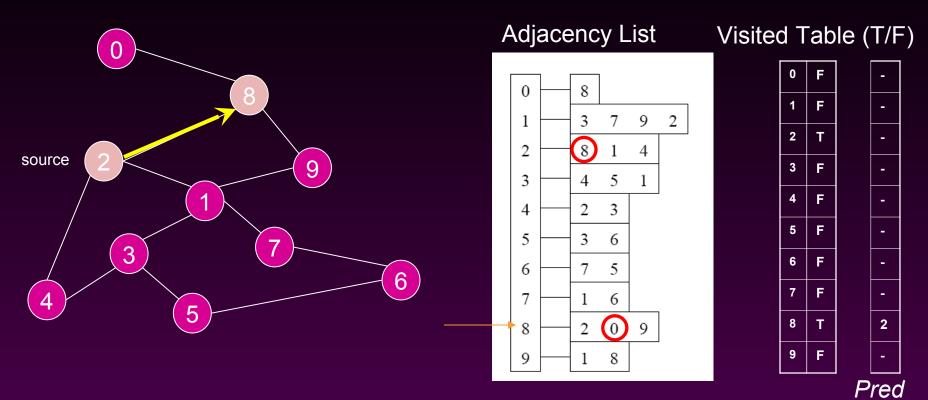
Initialize Pred to -1



Pred

Mark 2 as visited

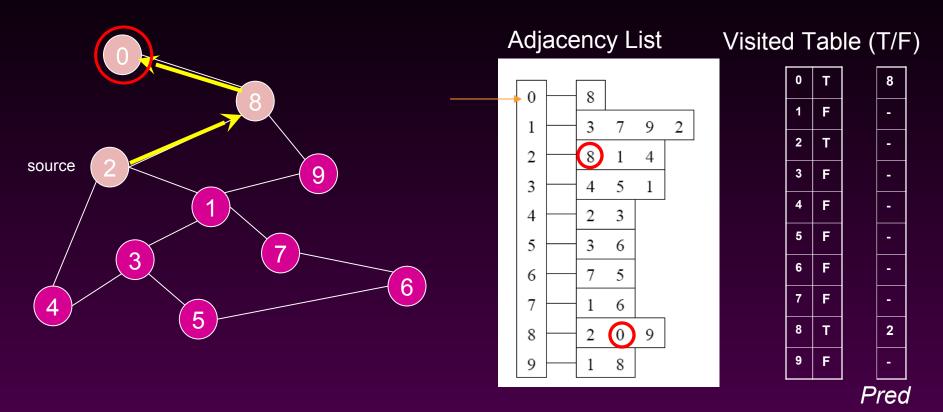
RDFS( 2 ) Now visit RDFS(8)



Mark 8 as visited

Recursive RDFS(2) calls RDFS(8) 2 is already visited, so visit RDFS(0)

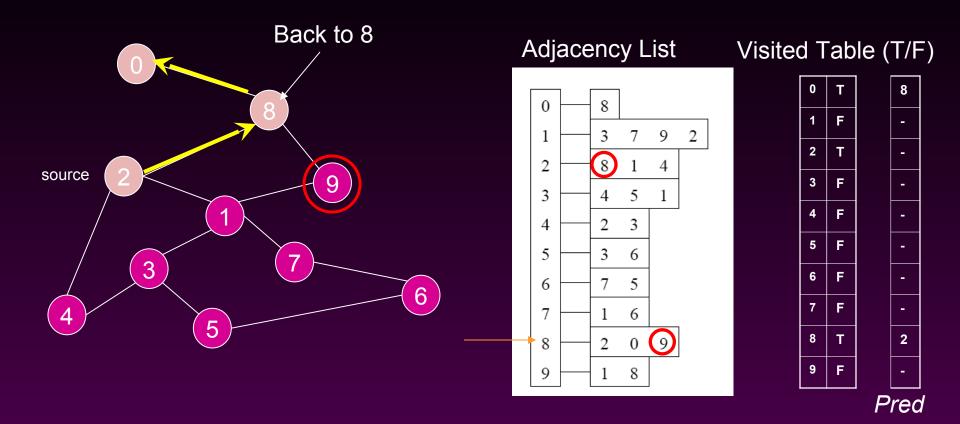
mark Pred[8]



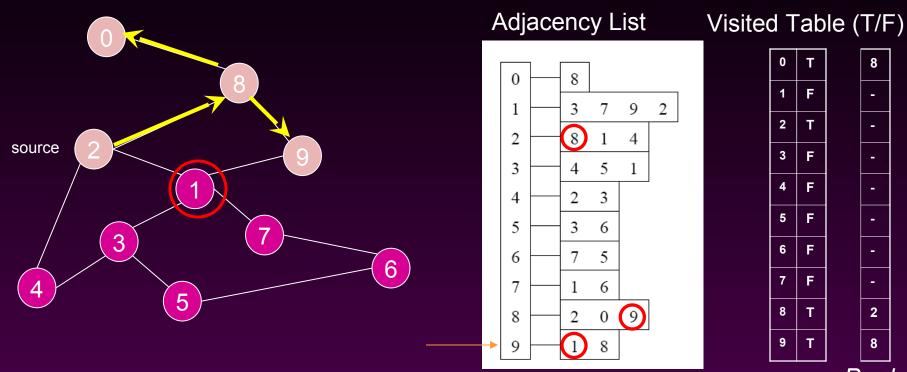
Mark 0 as visited

 Recursive calls
 RDFS(2)
 Mark Pred[0]

 RDFS(8)
 RDFS(0) -> no unvisited neighbors, return to call RDFS(8)



Recursive RDFS(2) calls RDFS(8) Now visit 9 -> RDFS(9)

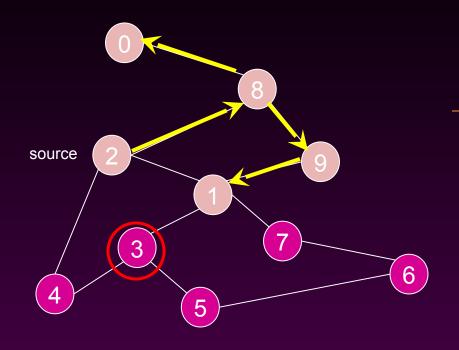


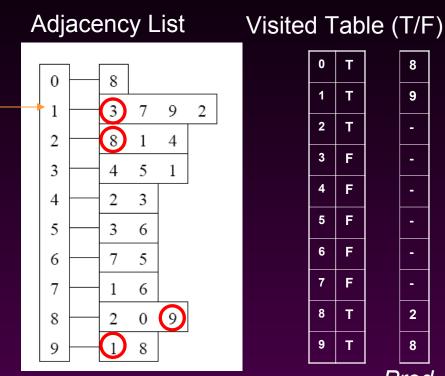
Pred

Mark 9 as visited

Recursive RDFS(2) calls RDFS(8) RDFS(9) -> visit 1, RDFS(1)

Mark Pred[9]



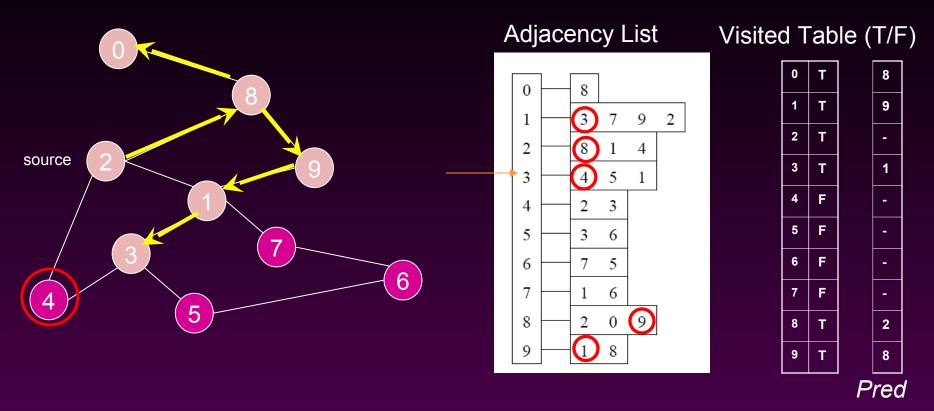


Pred

Mark 1 as visited

Mark Pred[1]

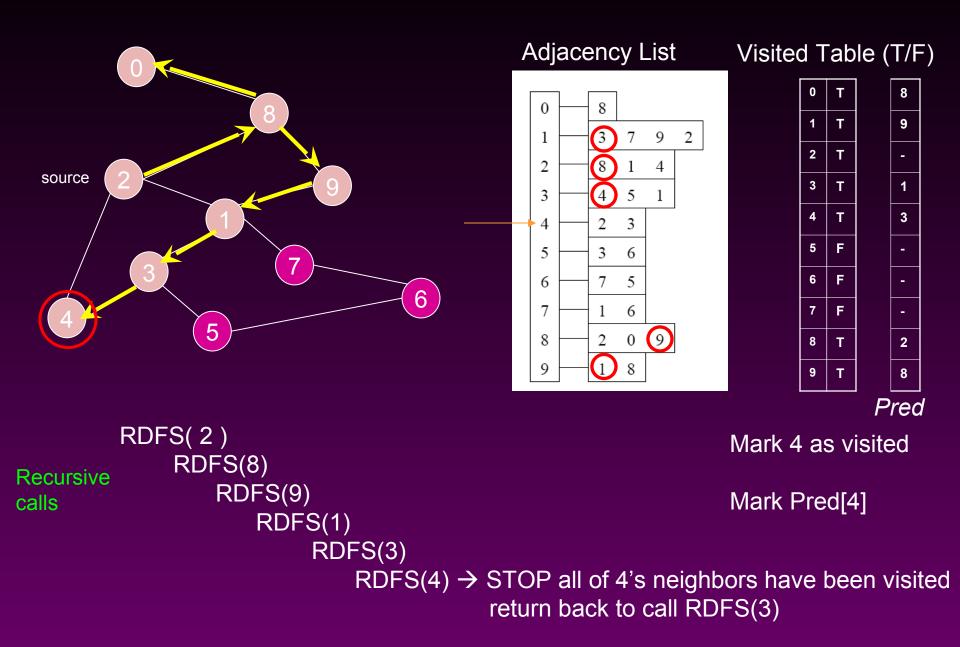
Recursive RDFS(2) calls RDFS(8) RDFS(9) RDFS(1) visit RDFS(3)

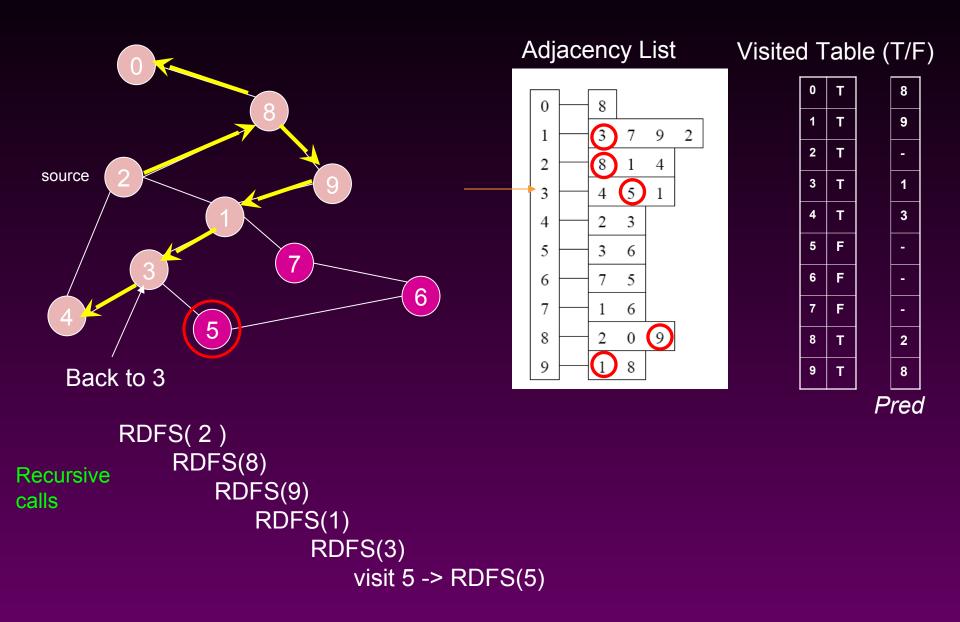


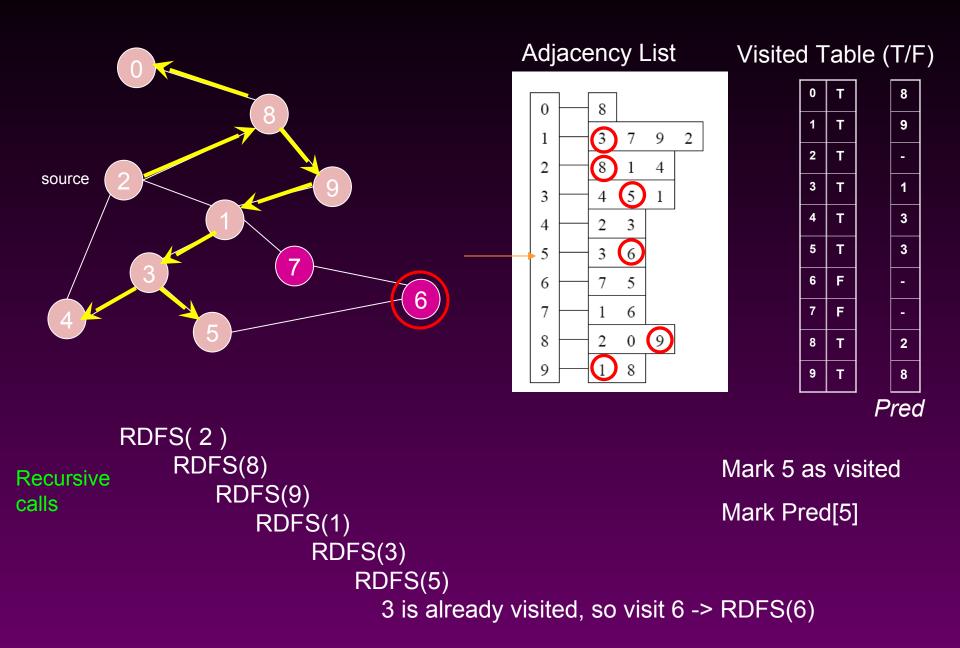
Mark 3 as visited

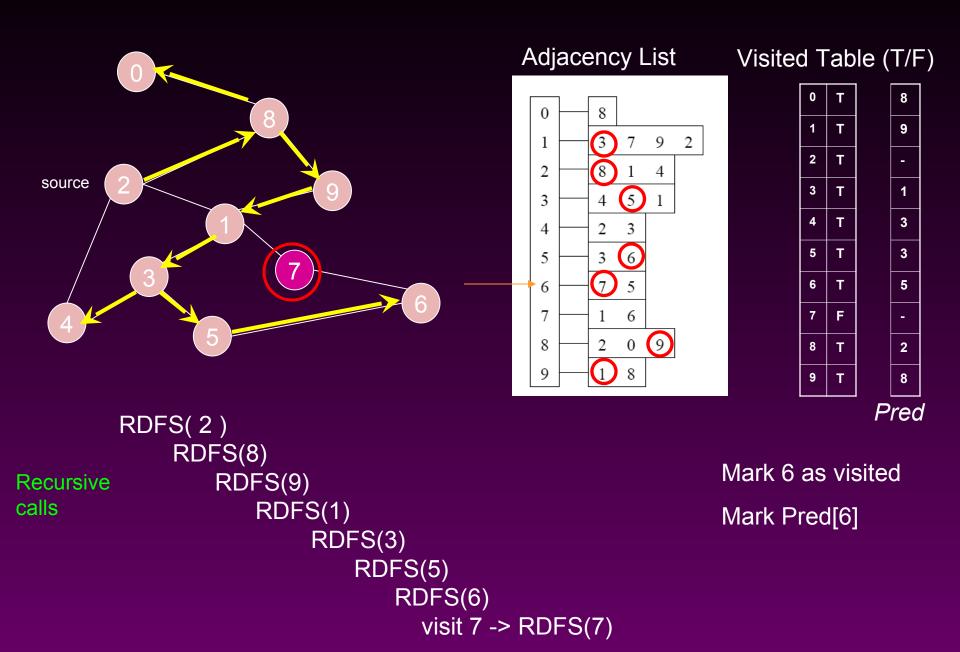
Mark Pred[3]

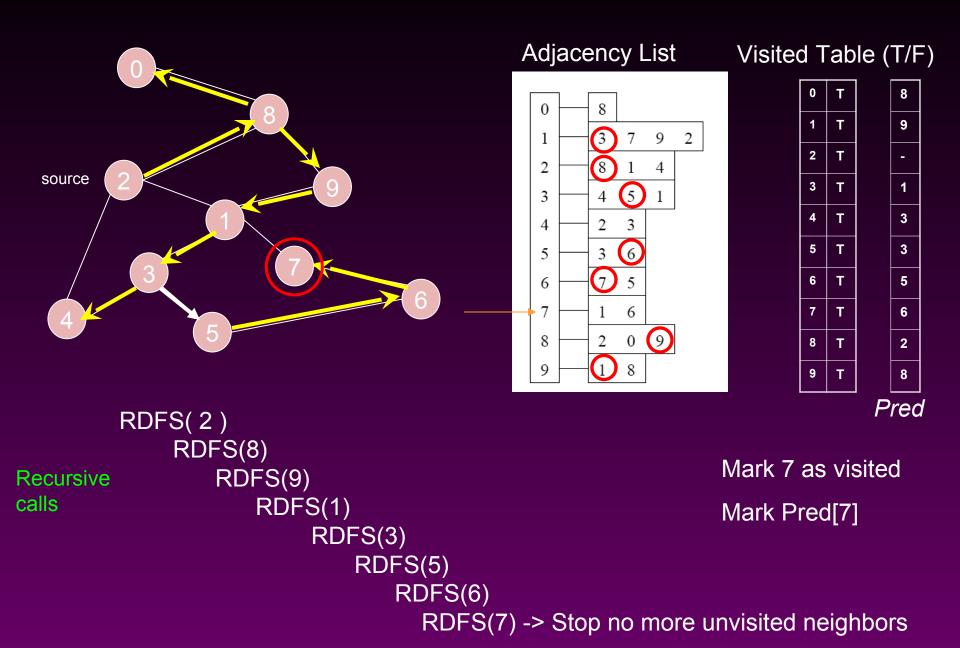
Recursive RDFS(2) calls RDFS(8) RDFS(9) RDFS(1) RDFS(1) RDFS(3) visit RDFS(4)

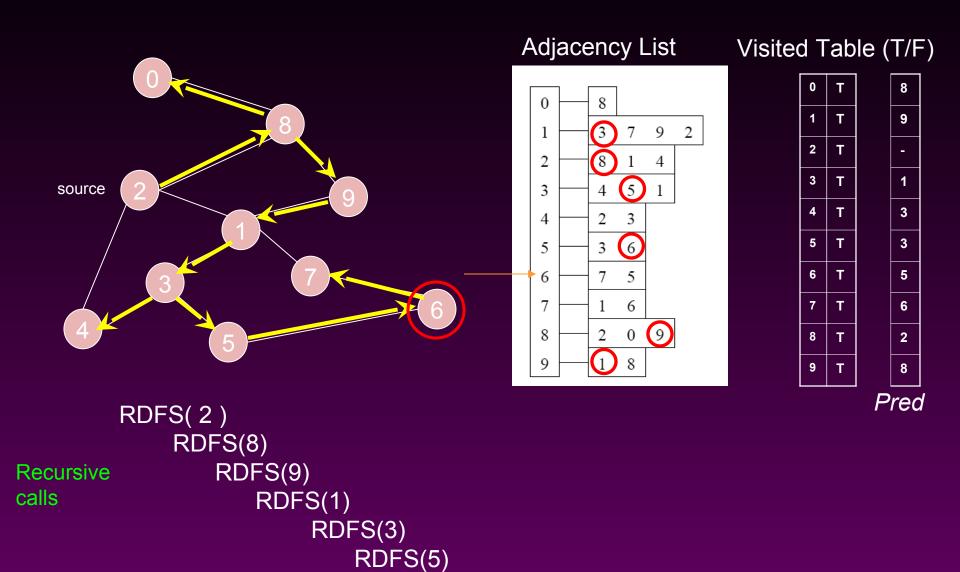




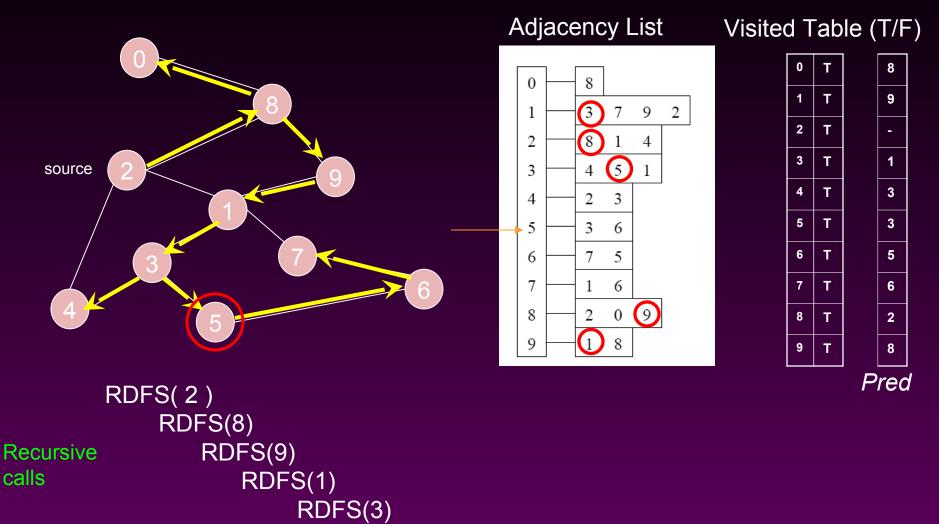




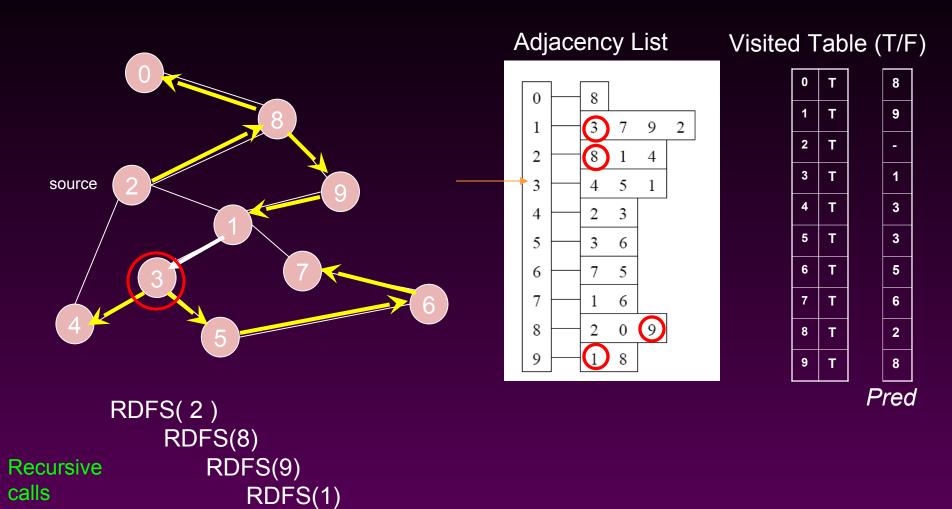




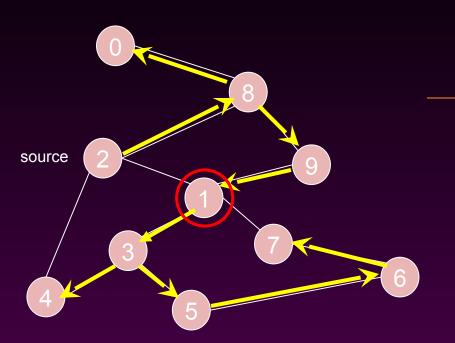
RDFS(6) -> Stop

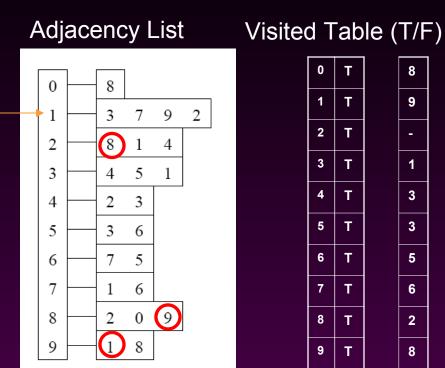


RDFS(5) -> Stop



RDFS(3) -> Stop





8

9

1

3

3

5

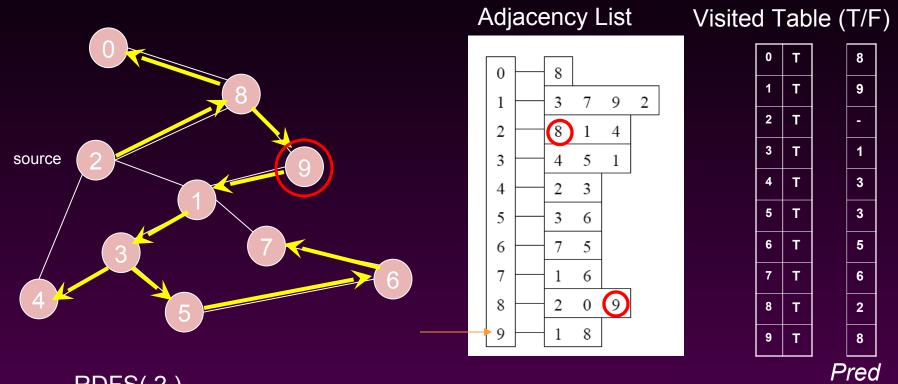
6

2

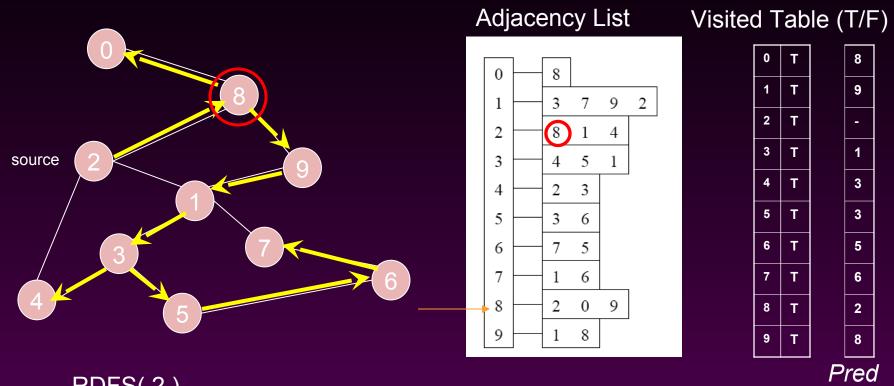
8

Pred

RDFS(2) RDFS(8) RDFS(9) Recursive RDFS(1) -> Stop calls



RDFS( 2 ) RDFS(8) Recursive RDFS(9) -> Stop calls

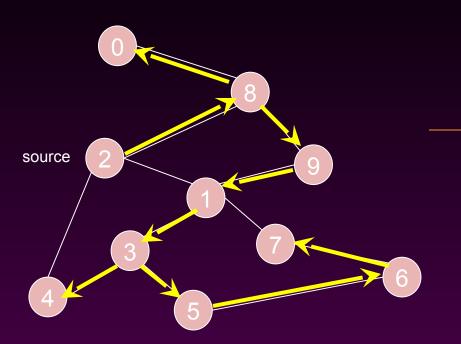


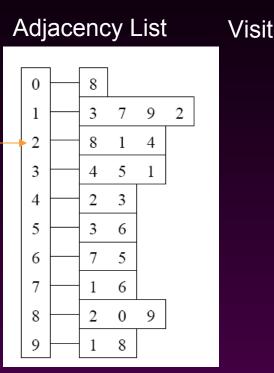
RDFS( 2 ) RDFS(8) -> Stop

Recursive calls

Graph / Slide 29

Example Finished





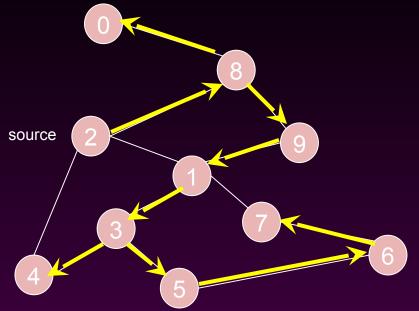
#### Visited Table (T/F)

0	Т		8
1	Т		9
2	Т		-
3	Т		1
4	Т		3
5	Т		3
6	Т		5
7	Т		6
8	Т		2
9	Т		8
Prec			

RDFS(2) -> Stop

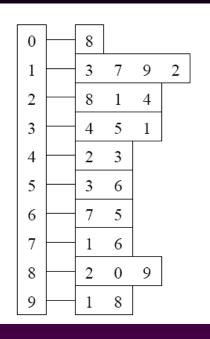
Recursive calls finished

### Graph / Slide 30 DFS Path Tracking





#### Visited Table (T/F)





#### DFS find out path too

#### **Algorithm** *Path*(*w*)

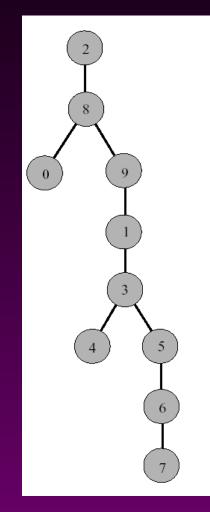
- 1. if  $pred[w] \neq -1$
- 2. **then**
- 3. *Path*(*pred*[*w*]);
- 4. output w

Try some examples. Path(0) -> Path(6) -> Path(7) -> Graph / Slide 31

## DFS Tree

Resulting DFS-tree. Notice it is much "deeper" than the BFS tree.





Captures the structure of the recursive calls - when we visit a neighbor w of v, we add w as child of v - whenever DFS returns from a

vertex v, we climb up in the tree from v to its parent

## Time Complexity of DFS (Using adjacency list)

We never visited a vertex more than once

- We had to examine all edges of the vertices
   We know Σ<sub>vertex v</sub> degree(v) = 2m where m is the number of edges
- So, the running time of DFS is proportional to the number of edges and number of vertices (same as BFS)
   O(n + m)
- You will also see this written as:
  O(hubble) hubble number of vertices (n)
  - O(|v|+|e|)|v| = number of vertices (n) edges (m)

|e| = number of