

Getting Mars Simulator ON your System

- 1- Go to course website http://profile.iiita.ac.in/bibhas.ghoshal/teaching_coa_2020.html and download the zip file of Mars simulator (Mars4_5.zip).
- 2- Extract the zip file and go into the folder Mars4_5.
- 3- Open a terminal here and install jdk required to run the simulator by typing
sudo apt-get install default-jdk.
(If you are having problem in this then try update once by typing `sudo apt-get update`)
- 4- After successful installation of jdk, start the simulator by typing in the terminal
java Mars

Directions for using the MARS simulator for MIPS assembly:

1. When the MARS simulator starts up, you can either:
 - a. Open an existing MIPS assembly file by:
From the menu bar select **File -> Open...** and then select the desired assembly program (the Desired **.asm** file) from the file chooser window.
 - b. Begin creating a new MIPS assembly file by:
From the menu bar select **File -> New.**
Then you can begin typing in MIPS assembly instructions into the Edit window, as Desired.

2. When ready, you may begin running/testing the assembly code by:

The environment of this simulator can be simplistically split to three segments:

- i. The *editor* at the upper left where all of the code is being written,
- ii. The *compiler/output* right beneath the editor and
- iii. The *list of registers* that represent the "CPU" for our program.

First assemble the code by selecting **Run -> Assembly** from the menu bar.

After assembling (by simply pressing F3) the environment changes, with two new segments getting the position of the editor: the text segment where

- i) Each line of assembly code gets cleared of "*pseudo instructions*" at the "*basic*" column
- ii) The machine code for each instruction at the "code" column, and the data segment where we can have a look at a representation of the memory of a processor with little-endian order.

3. Run the compiled code:

Run the code using either the **Run -> Go** option,
Which will execute the program to completion, or

The **Run -> Step** option, which will execute only one instruction at a time.

You may likewise use the corresponding buttons for *Go* or *Step* available under the menu bar (or use the F5 or F7 keys, which correspond to *Go* and *Step*. These buttons and key

shortcuts are particularly useful for Step, since you need to push/execute Step each time you want to execute the next instruction in the program).

4. Debug: To see what's going on while the program is being executed, look at the registers in the '**Register**' window, which is the right-most window in the display. Notice that this displays the current values of all the registers, including the \$s and \$t registers, and even the **program counter (pc)**.

Note: By default, the register values are shown in hexadecimal. If you would prefer to see their decimal values, in the menu bar, de-select Settings -> Values displayed in hexadecimal.

If you create a new assembly program or make modifications to an existing assembly program, you can save the code to a .asm file using the **File -> Save or File -> Save as...** options from the menu bar.

6. The registers:

- i. \$zero -Constant Register (value 0)
- ii. \$a registers - to pass arguments
- iii. \$t registers – to store information
- iv. \$s registers – to store information (allow contents to be saved on the stack)
- v. \$k registers – kernel registers
- vi. sp – stack pointer
- vii. \$fp- frame pointer
- viii. \$ra – return address register (will be used for subroutine calls)
- ix. \$v registers - to hold the arguments for system calls
- x. \$f registers – floating point registers available from the co-processor (will be used for floating point operations)

7. The first assembly program: Hello World

i. The hello_world.asm file will have two sections: data (to hold the data of the program) and text (to hold the instructions and pseudo instructions)

```
.data                                #data section  
str: .asciiz "Hello world\n" # we define a variable called str having data type ascii and holding the  
string Hello world with a new line character at the end. This variable  
called str is loaded in the data memory during compile time  
  
.text                                #code section  
  
li    $v0, 4                          #system call for printing strings  
la    $a0, str                        #loading our string from data section to the $a0 register;  
la stands for load the address, where address refers to the first  
address of the string of characters named as str  
syscall                               # the system is instructed to print the value pointed to by the address  
loaded in $a0
```

Before illustrating the results through MARS, a little more explanation about these commands is needed:

System calls are a set of services provided from the operating system. To use a system call, a call code is needed to be put to \$v0 register for the needed operation. If a system call has arguments, those are put at the \$a0-\$a2 registers. Here are all the system calls.

li (load immediate) is a pseudo-instruction (we'll talk about that later) that instantly loads a register with a value.

la (load address) is also a pseudo-instruction that loads an address to a register.

With `li $v0, 4` the \$v0 register has now 4 as value, while `la $a0, str` loads the string of str to the \$a0 register.

A word is (as much as we are talking about MIPS) a 32 bits sequence, with bit 31 being the Most Significant Bit and bit 0 being the Least Significant Bit.

lw (load word) transfers from the memory to a register, while sw (store word) transfers from a register to the memory. With the `lw $s1, 0($t0)` command, we loaded to \$s1 register the value that was at the LSB of the \$t0 register (that's what the 0 symbolizes here, the offset of the word), aka 256. \$t0 here has the address, while \$s1 has the value. `sw $t2, 0($t0)` does just the opposite job.

MARS uses the Little Endian, meaning that the LSB of a word is stored to the smallest byte address of the memory.

MIPS uses byte addresses, so an address is a part of its previous and next by 4.

By assembling the code from before, we can further understand how memory and registers exchange, disabling "Hexadecimal Values" from the Data Segment: or enabling "ASCII" from the Data Segment: