

# Petri Nets

Jian-Jia Chen  
(slides are based on  
Peter Marwedel)  
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# Models of computation considered in this course

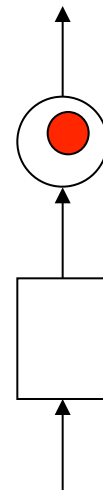
| Communication/<br>local computations   | Shared<br>memory                                     | Message passing  |                       |
|--|--|--|-----------------------|
|  |  | Synchronous  | Asynchronous          |
| Undefined<br>components                | Plain text, use cases<br>  (Message) sequence charts |  |                       |
| Communicating finite<br>state machines | StateCharts  |  | SDL                   |
| Data flow                              |  |  | Kahn networks,<br>SDF |
| <b>Petri nets</b>                      |  | <b>C/E nets, P/T nets, ...</b>                               |                       |
| Discrete event (DE)<br>model           | VHDL*,<br>Verilog*,<br>SystemC*, ...                 | Only experimental systems, e.g.<br>distributed DE in Ptolemy |                       |
| Von Neumann model                      | C, C++, Java   | C, C++, Java with libraries<br>CSP, ADA                      |                       |

# Introduction

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Introduced in 1962 by Carl Adam Petri in his PhD thesis.  
Focus on modeling causal dependencies;  
no global synchronization assumed (message passing only).  
Key elements:

- **Conditions**  
Either met or not met.
- **Events**  
May take place if certain conditions are met.
- **Flow relation**  
Relates conditions and events.



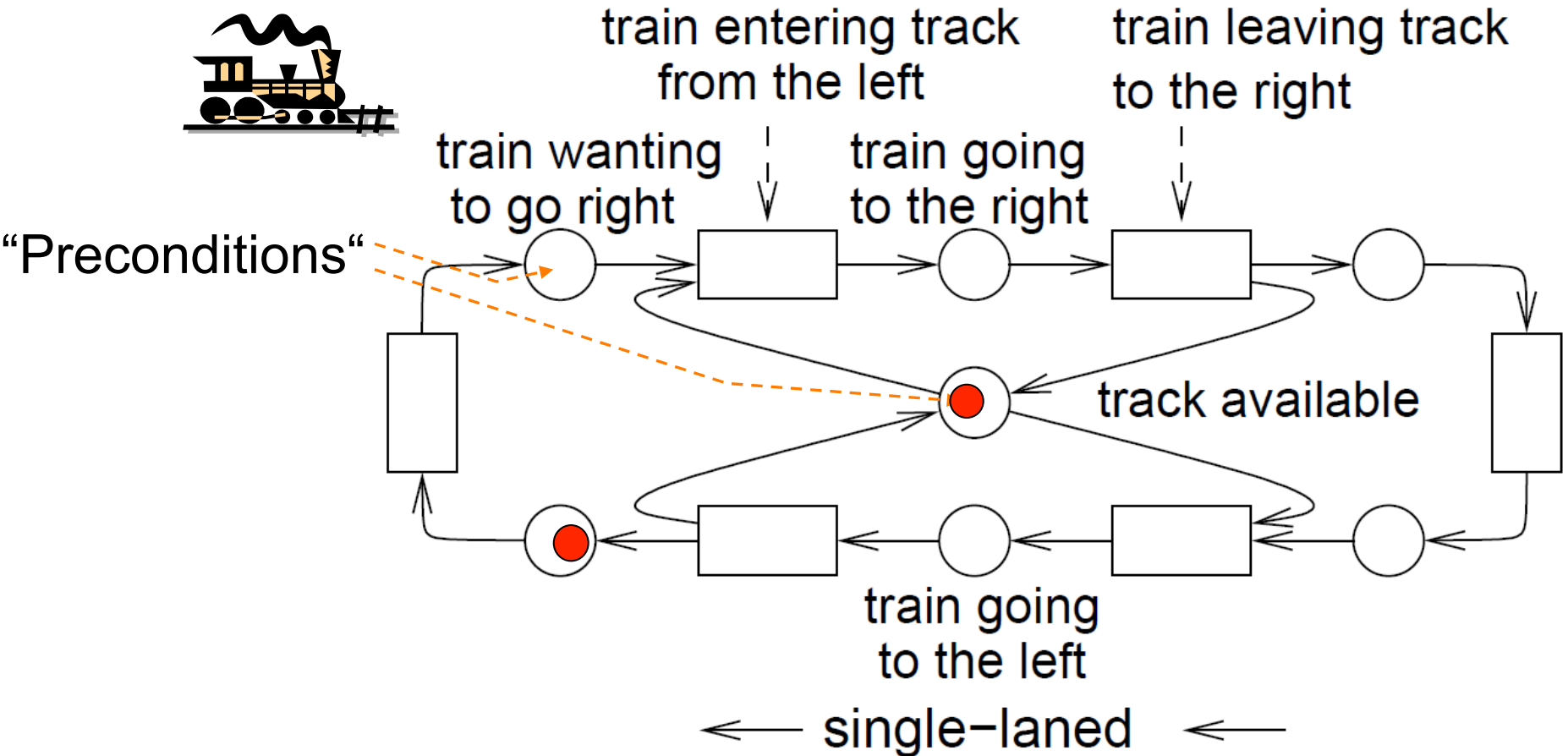
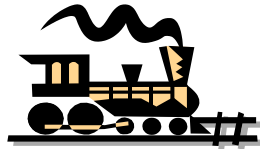
Conditions, events and the flow relation form  
a **bipartite graph** (graph with two kinds of nodes).

# Interactive Example

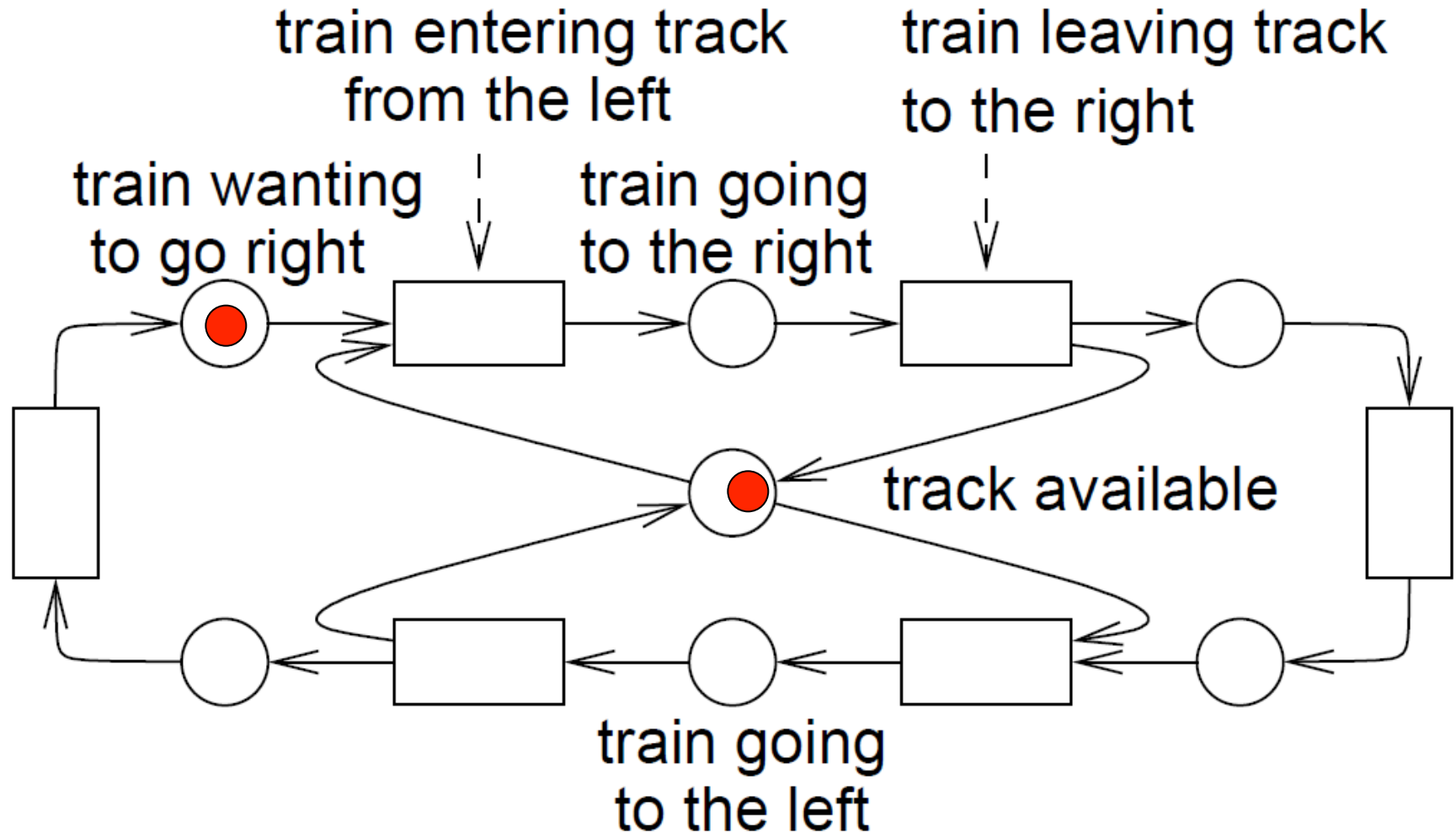
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<http://www.informatik.uni-hamburg.de/TGI/PetriNets/introductions/aalst/>

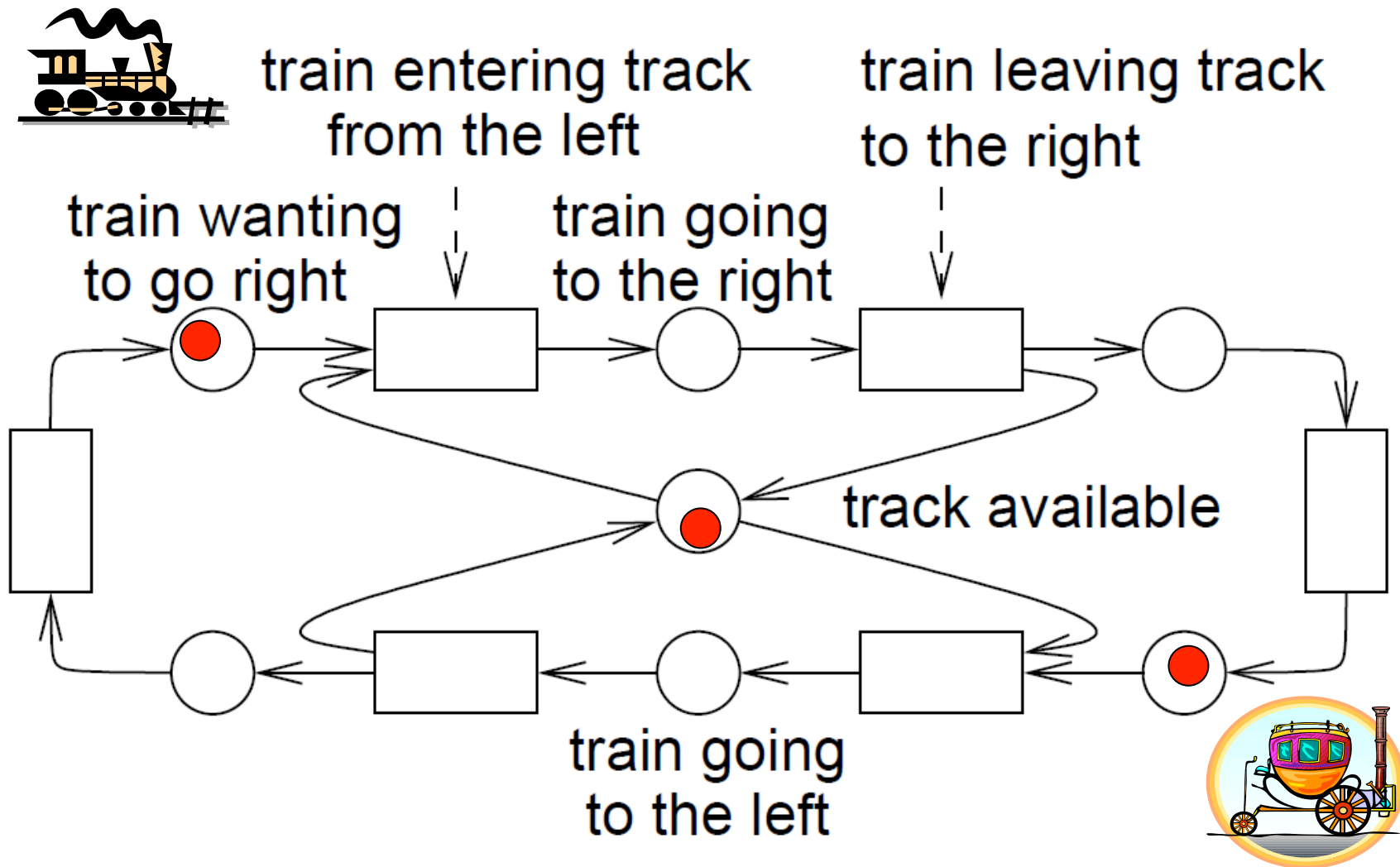
# Example: Synchronization at single track rail segment



# Playing the “token game“



# Conflict for resource "track"



# Condition/event nets

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**Def.:**  $N=(C,E,F)$  is called a **net**, if the following holds

1.  $C$  and  $E$  are disjoint sets
2.  $F \subseteq (C \times E) \cup (E \times C)$ ; is binary relation,  
 (“**flow relation**“)



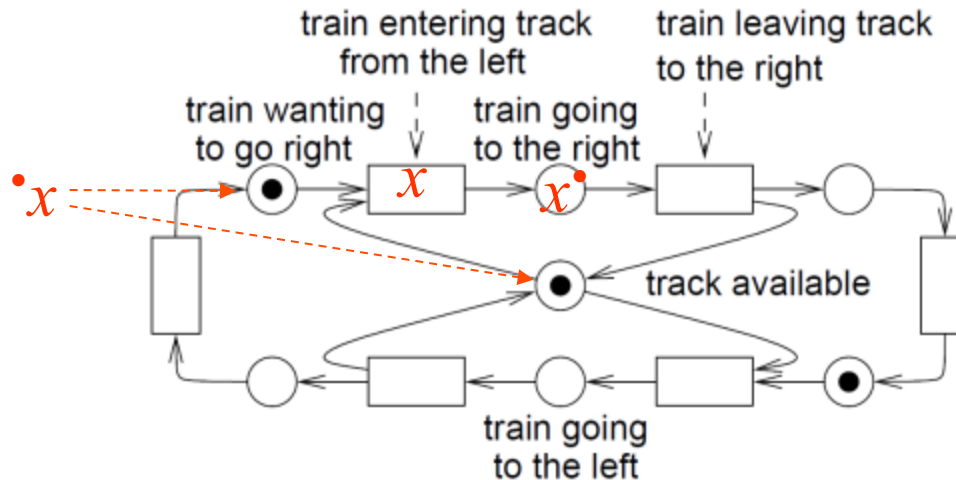
# Pre- and post-sets

**Def.:** Let  $N$  be a net and let  $x \in (C \cup E)$ .

$\bullet x := \{y \mid y F x\}$  is called the **pre-set** of  $x$ ,  
(or **preconditions** if  $x \in E$ )

$x^\bullet := \{y \mid x F y\}$  is called the set of **post-set** of  $x$ ,  
(or **postconditions** if  $x \in E$ )

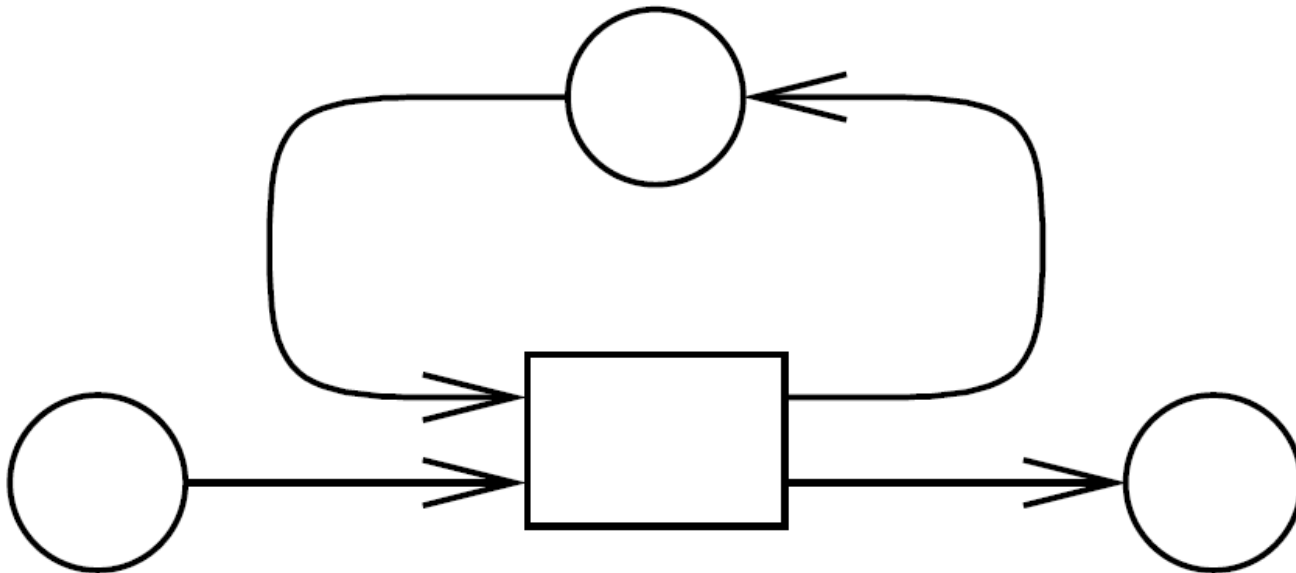
**Example:**



# Loops and pure nets

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**Def.:** Let  $(c,e) \in C \times E$ .  $(c, e)$  is called a **loop** if  $cFe \wedge eFc$ .

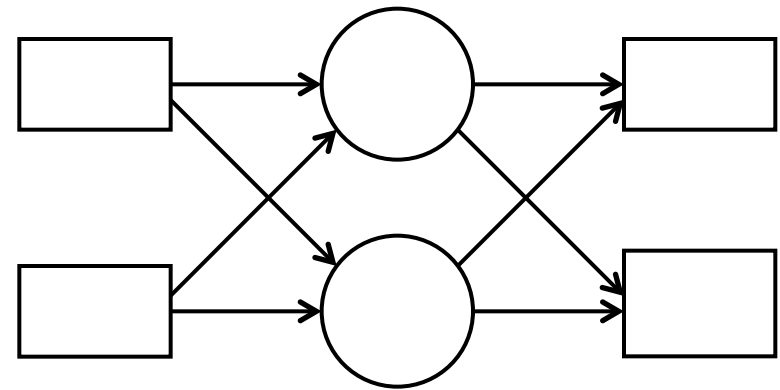
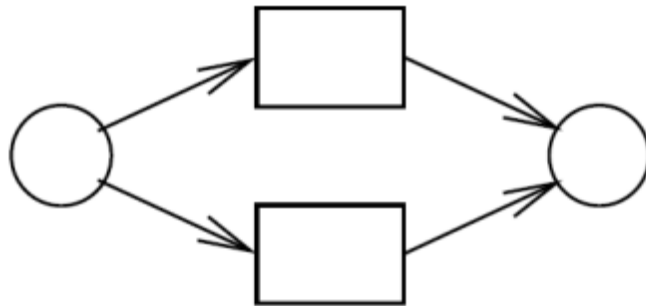


**Def.:** Net  $N=(C,E,F)$  is called **pure**, if  $F$  does not contain any loops.

# Simple nets

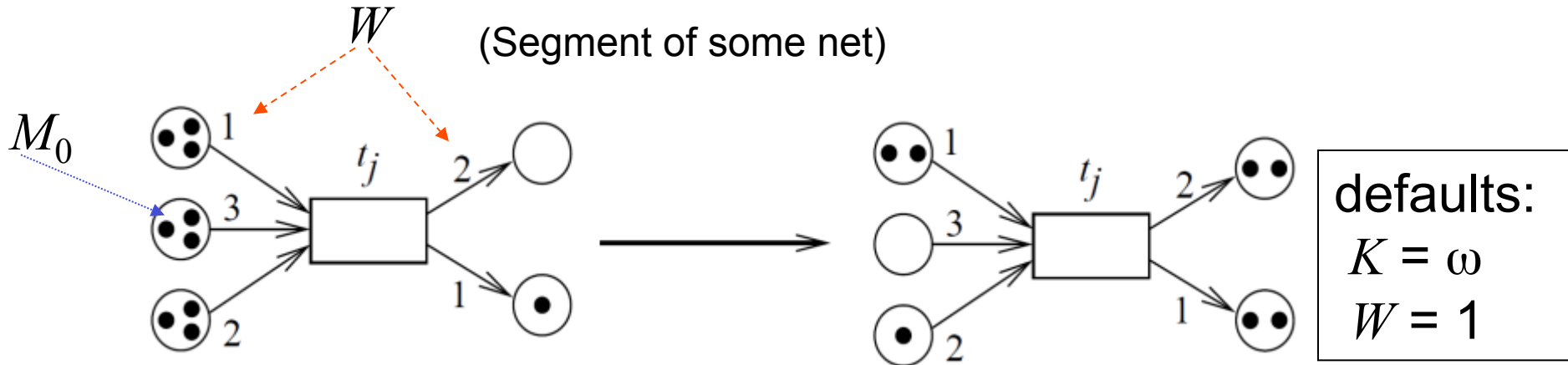
**Def.:** A net is called **simple** if no two nodes  $n_1$  and  $n_2$  have the same pre-set and post-set.

Example (not simple nets):



**Def.:** Simple nets with no isolated elements meeting some additional restrictions are called **condition/event nets (C/E nets)**.

# Place/transition nets



**Def.:**  $(P, T, F, K, W, M_0)$  is called a **place/transition net** if

1.  $N=(P, T, F)$  is a **net** with places  $p \in P$  and transitions  $t \in T$
2.  $K: P \rightarrow (N_0 \cup \{\omega\}) \setminus \{0\}$  denotes the **capacity** of places ( $\omega$  symbolizes infinite capacity)
3.  $W: F \rightarrow (N_0 \setminus \{0\})$  denotes the **weight of graph edges**
4.  $M_0: P \rightarrow N_0 \cup \{\omega\}$  represents the **initial marking** of places

# Applications

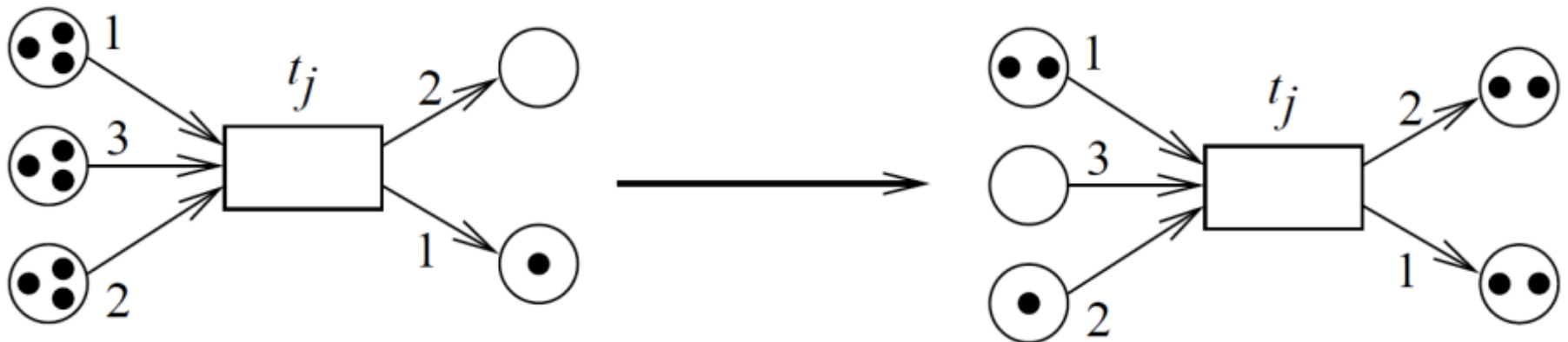
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- Modeling of resources;
- modeling of mutual exclusion;
- modeling of synchronization.

# Computing changes of markings

“Firing” transitions  $t$  generate new markings on each of the places  $p$  according to the following rules:

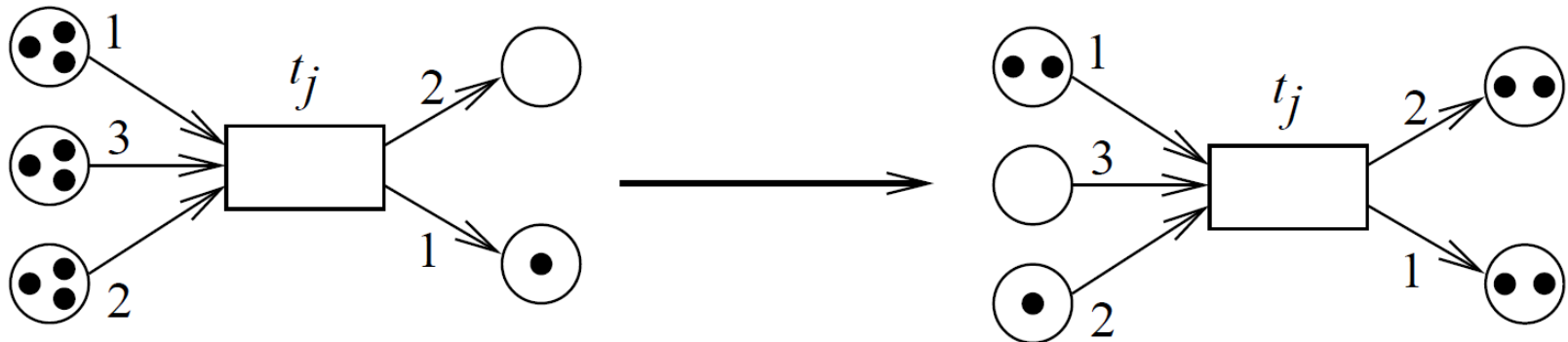
$$M'(p) = \begin{cases} M(p) - W(p, t), & \text{if } p \in \bullet t \setminus t^\bullet \\ M(p) + W(t, p), & \text{if } p \in t^\bullet \setminus \bullet t \\ M(p) - W(p, t) + W(t, p), & \text{if } p \in \bullet t \cap t^\bullet \\ M(p) & \text{otherwise} \end{cases}$$



# Activated transitions

Transition  $t$  is “activated“ if

$$(\forall p \in \bullet t : M(p) \geq W(p,t)) \wedge (\forall p \in t^\bullet : M(p) + W(t,p) \leq K(p))$$



Activated transitions can “take place“ or “fire“, but don’t have to.

We never talk about “time“ in the context of Petri nets.

The order in which activated transitions fire, is not fixed (it is non-determinate).

# Shorthand for changes of markings

Slide 12:

$$M'(p) = \begin{cases} M(p) - W(p,t), & \text{if } p \in \bullet t \setminus t \bullet \\ M(p) + W(t,p), & \text{if } p \in t \bullet \setminus \bullet t \\ M(p) - W(p,t) + W(t,p), & \text{if } p \in \bullet t \cap t \bullet \\ M(p) & \text{otherwise} \end{cases}$$

Let

$$\underline{t}(p) = \begin{cases} -W(p,t) & \text{if } p \in \bullet t \setminus t \bullet \\ +W(t,p) & \text{if } p \in t \bullet \setminus \bullet t \\ -W(p,t) + W(t,p) & \text{if } p \in \bullet t \cap t \bullet \\ 0 & \end{cases}$$

⇒  $\forall p \in P: M'(p) = M(p) + \underline{t}(p)$

⇒  $M' = M + \underline{t}$       +: vector add



# Matrix $\underline{N}$ describing all changes of markings

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$$\underline{t}(p) = \begin{cases} -W(p,t) & \text{if } p \in \bullet t \setminus t \bullet \\ +W(t,p) & \text{if } p \in t \bullet \setminus \bullet t \\ -W(p,t) + W(t,p) & \text{if } p \in \bullet t \cap t \bullet \\ 0 & \text{otherwise} \end{cases}$$

Def.: Matrix  $\underline{N}$  of net  $N$  is a mapping

$$\underline{N}: P \times T \rightarrow \mathbb{Z} \text{ (integers)}$$

such that  $\forall t \in T : \underline{N}(p,t) = \underline{t}(p)$

Component in column  $t$  and row  $p$  indicates the change of the marking of place  $p$  if transition  $t$  takes place.

For pure nets,  $(\underline{N}, M_0)$  is a complete representation of a net.

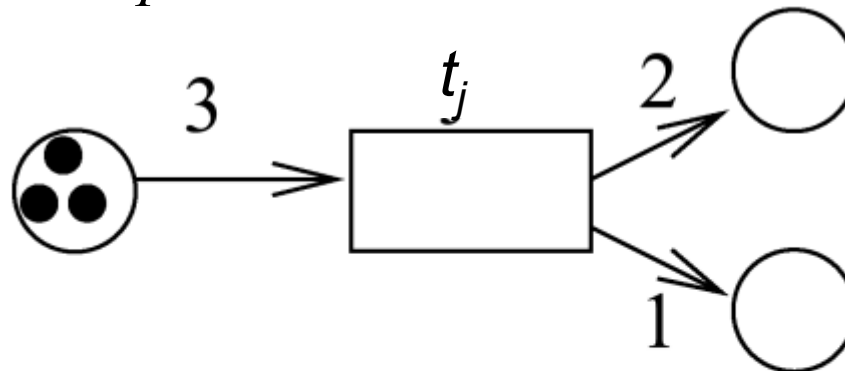
# Place - invariants

Standardized technique for proving properties of system models

For any transition  $t_j \in T$  we are looking for sets  $R \subseteq P$  of places for which the accumulated marking is constant:

$$\sum_{p \in R} t_{-j}(p) = 0$$

Example:



# Predicate/transition nets

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Goal: compact representation of complex systems.

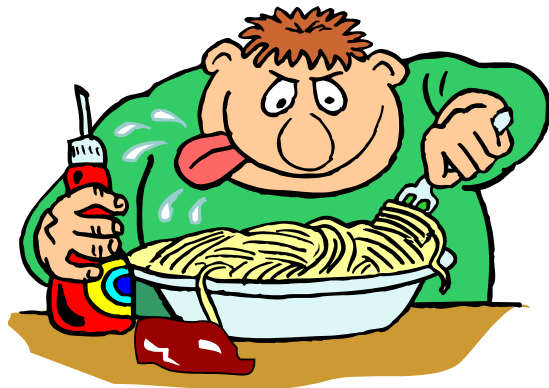
Key changes:

- Tokens are becoming individuals;
- Transitions enabled if functions at incoming edges true;
- Individuals generated by firing transitions defined through functions

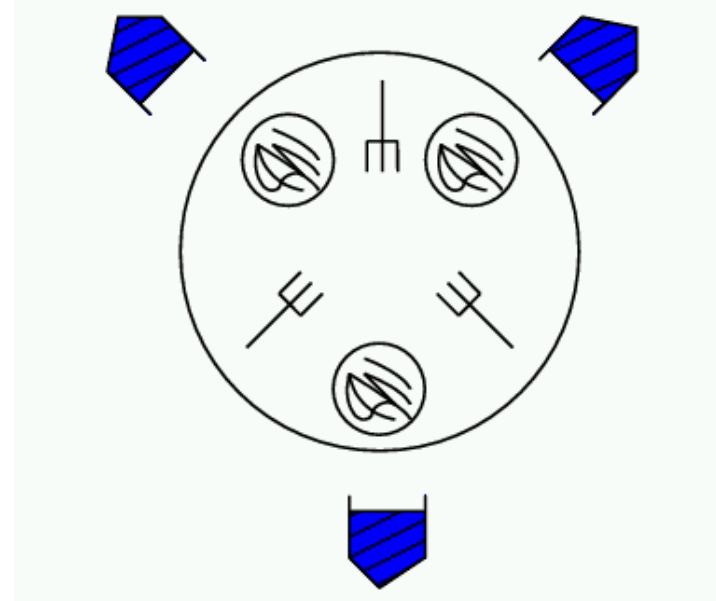
Changes can be explained by folding and unfolding C/E nets,  
☞ semantics can be defined by C/E nets.

# Example: Dining philosophers problem

$n > 1$  philosophers sitting at a round table;  
 $n$  forks,  
 $n$  plates with spaghetti;  
philosophers either thinking or eating spaghetti (using left and right fork).



2 forks needed!

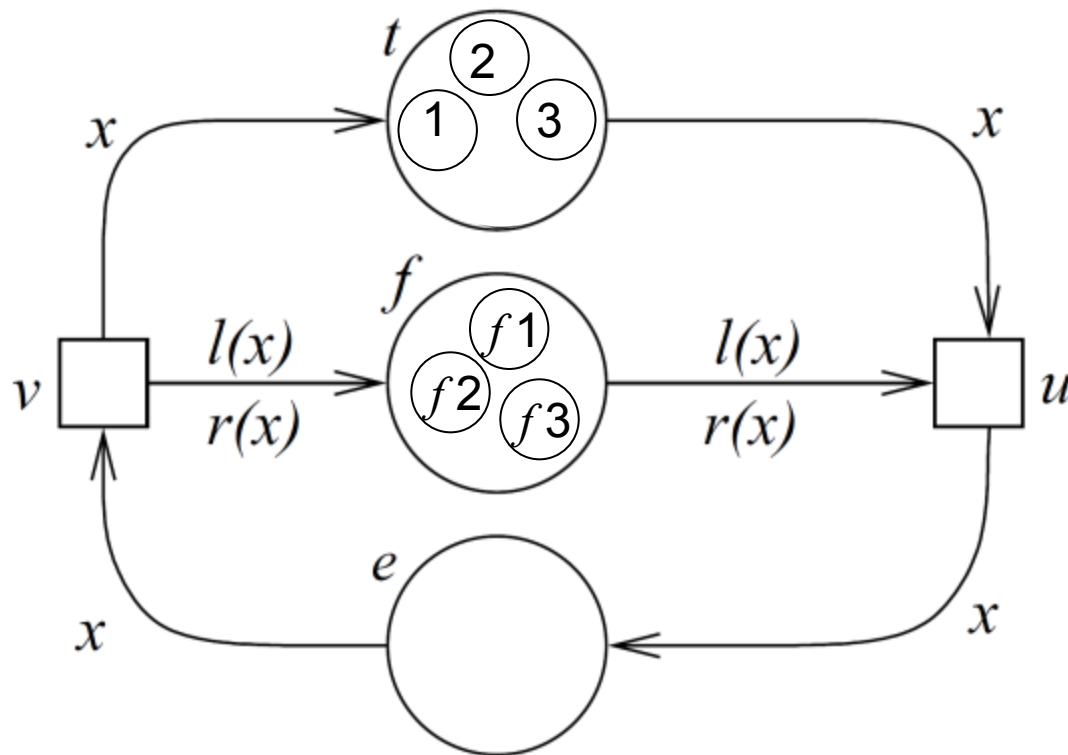


How to model conflict for forks?  
How to guarantee avoiding starvation?



# Predicate/transition model of the dining philosophers problem (1)

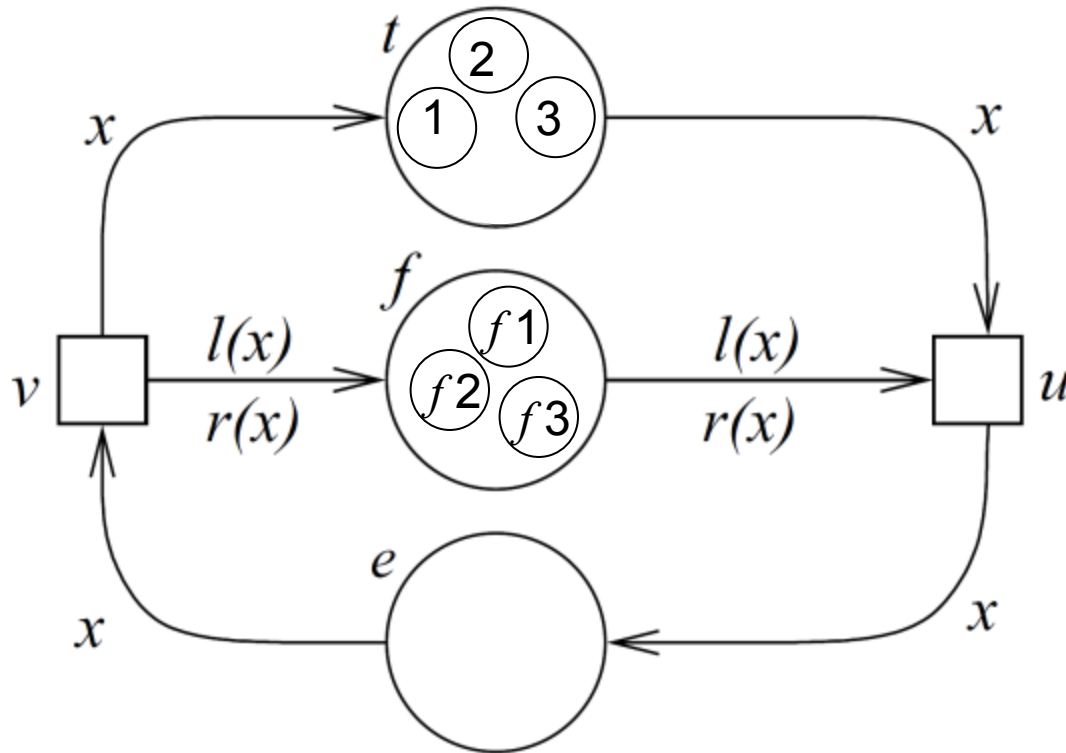
Let  $x$  be one of the philosophers,  
let  $l(x)$  be the left fork of  $x = fx$ ,  
let  $r(x)$  be the right fork of  $x = f(x+1)$ .  
 $l(2) = f2$ ,  $r(2) = f3$



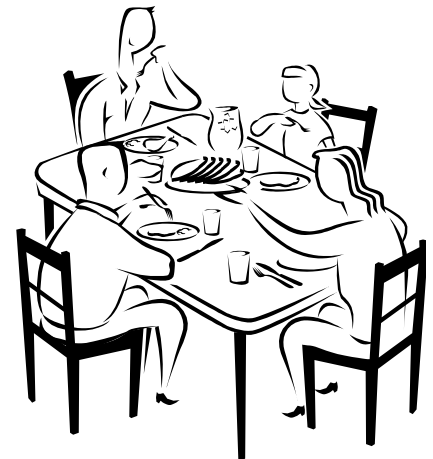
Tokens:  
individuals.

Semantics can be  
defined by  
replacing net by  
equivalent  
condition/event  
net.

# Predicate/transition model of the dining philosophers problem (2)



Model can be extended to arbitrary numbers of people.



# Evaluation

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## Pros:

- Appropriate for distributed applications,
- Well-known theory for formally proving properties,

## Cons (for the nets presented) :

- problems with modeling timing,
- no programming elements,
- no hierarchy.

## Extensions:

- Enormous amounts of efforts on removing limitations.



# Summary

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Petri nets: focus on causal dependencies

- Condition/event nets
  - Single token per place
- Place/transition nets
  - Multiple tokens per place
- Predicate/transition nets
  - Tokens become individuals
  - Dining philosophers used as an example